

# How American Politics Ensures Electoral Accountability in Congress<sup>1</sup>

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<sup>1</sup>Joint with Danny Ebanks & Jonathan N. Katz (thanks to Aleksandra Conevska)

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## The Plan

Model Validation: Out-of-sample tests

Prob(Incumbent Defeat): High, No Change

Intermediate Variables: Massive Change

How No Change Leads to Massive Change

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  - Different combos of {Polarization, Partisanship, IncAd, Marginals, Gerrymandering bias}  $\leadsto$  the same Prob(Defeat)

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  - Interpret: to understand the big picture

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$$v_{it} \sim \mathcal{N}(\mu_{it}, \sigma^2) \quad \text{Regression}$$

$$\mu_{it} = X_{it} \beta_t$$

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- Extensions: uncontested outcomes; > 2 parties

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- Ablation studies: every component essential
- Extensions: uncontested outcomes; > 2 parties
- Computation: extensive but easy; ElectIt Software



The Plan

**Model Validation: Out-of-sample tests**

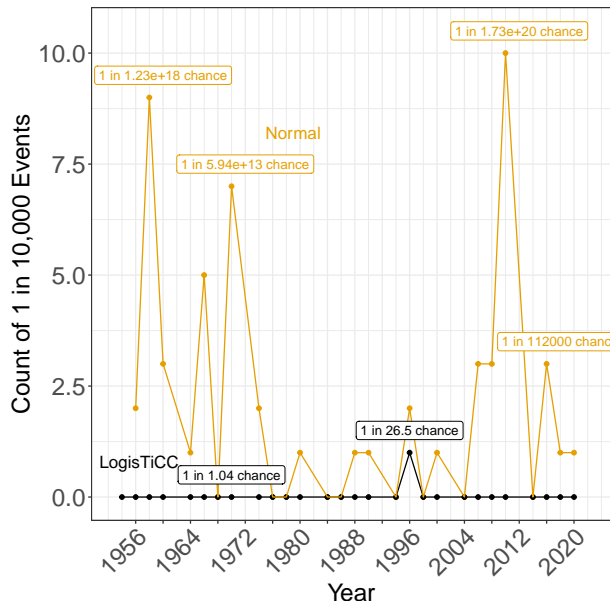
Prob(Incumbent Defeat): High, No Change

Intermediate Variables: Massive Change

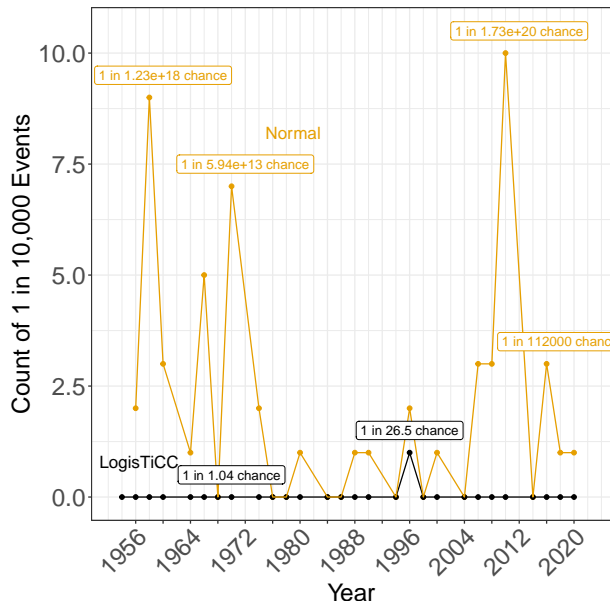
How No Change Leads to Massive Change

# “Moral Certitude”: Elections outside 99.99% CI

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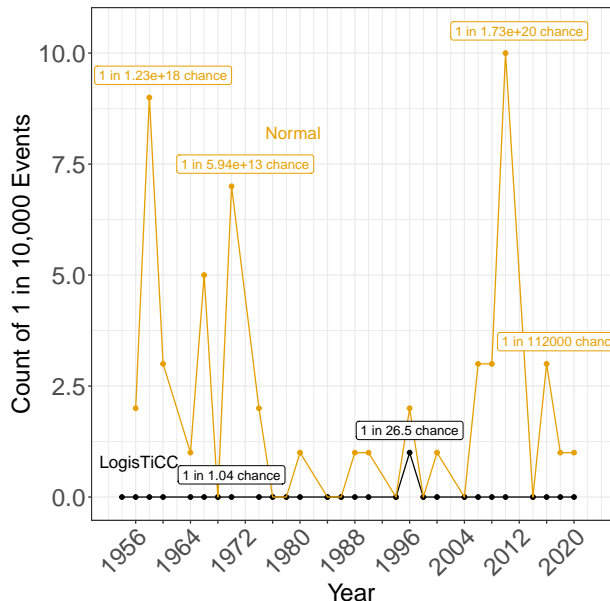


# “Moral Certitude”: Elections outside 99.99% CI



1-in-10K Events:

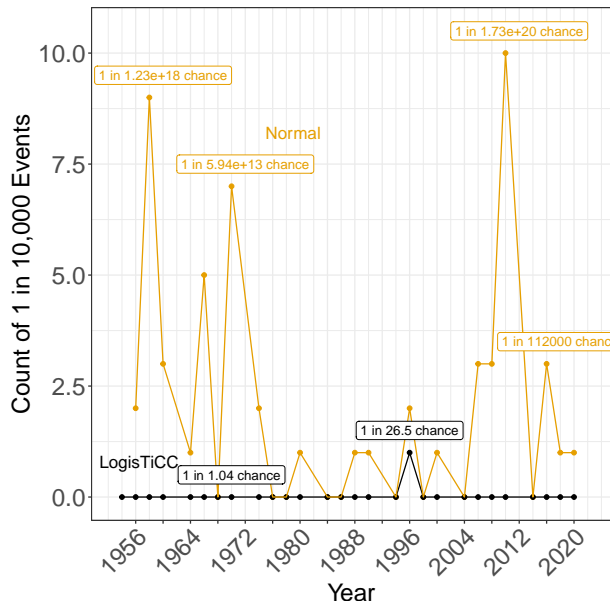
# “Moral Certitude”: Elections outside 99.99% CI



1-in-10K Events:

LogisTiCC:  
1 in 10K

# “Moral Certitude”: Elections outside 99.99% CI



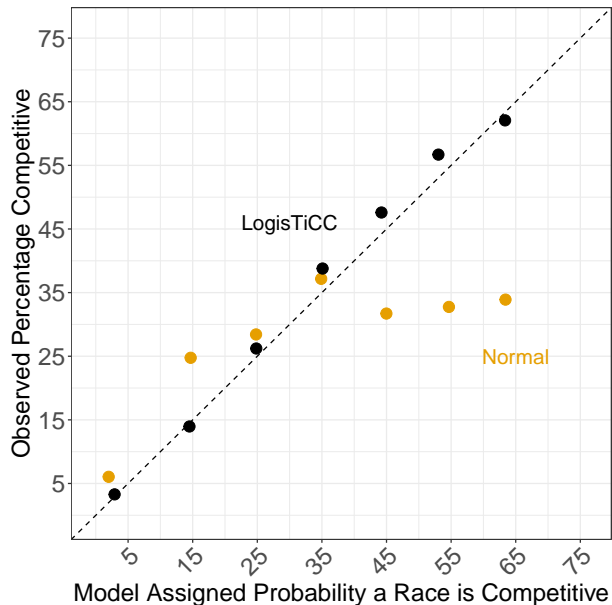
1-in-10K Events:

LogisTiCC:  
1 in 10K

Normal:  
All the time!

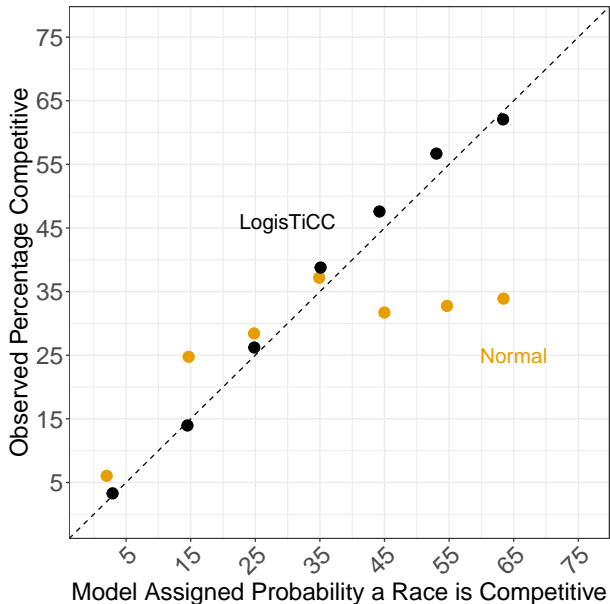
# Competitiveness Calibration

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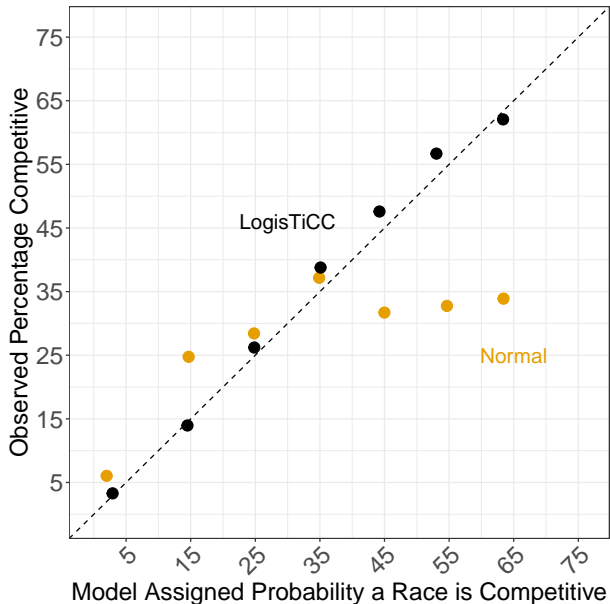


# Competitiveness Calibration



LogisTiCC: Near perfect

# Competitiveness Calibration



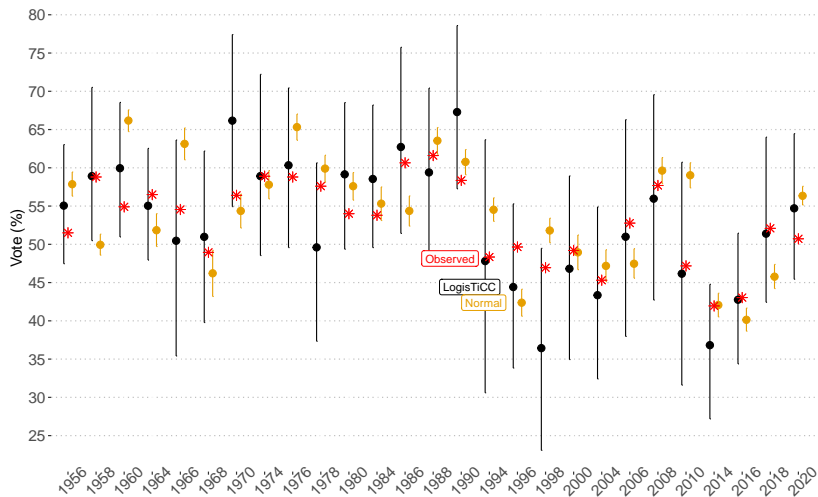
LogisTiCC: Near perfect

Normal: Fails for the most important elections

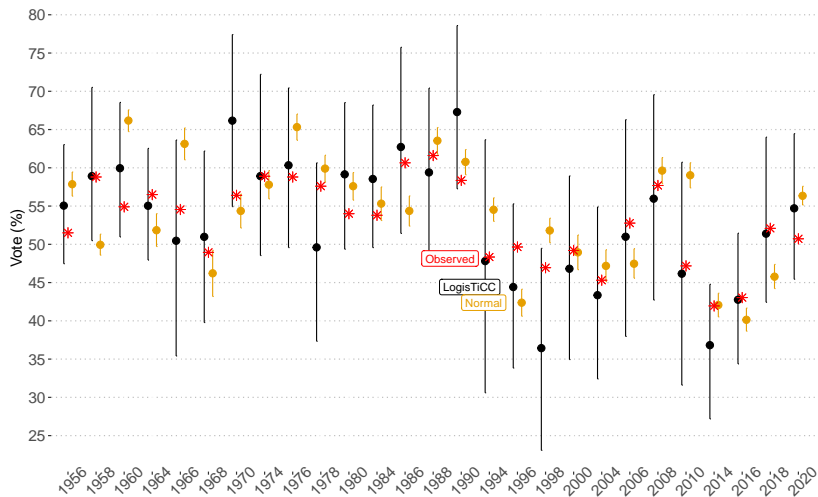
## 95% CI Coverage:

# 95% CI Coverage: Median House Seat Expected Vote

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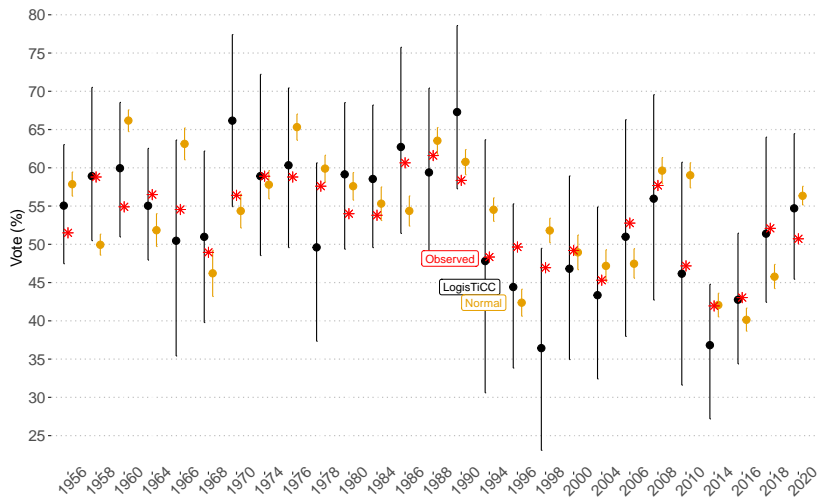


# 95% CI Coverage: Median House Seat Expected Vote



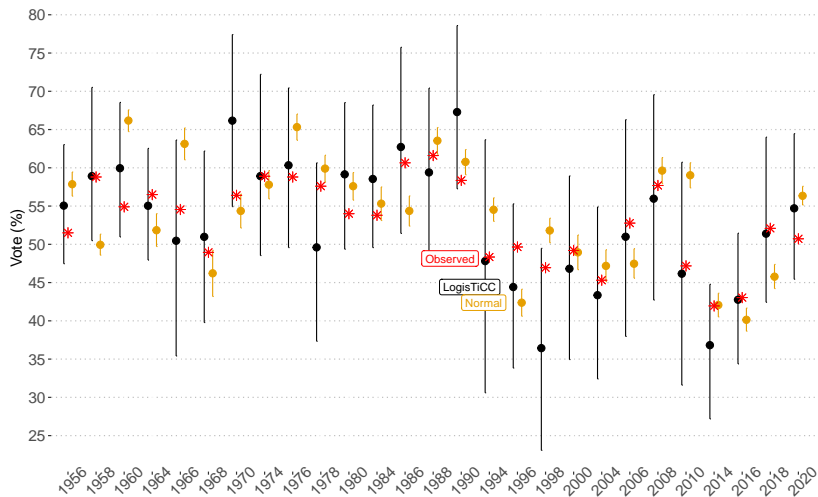
95% CI captures

# 95% CI Coverage: Median House Seat Expected Vote



95% CI captures (Theory: 26/27):

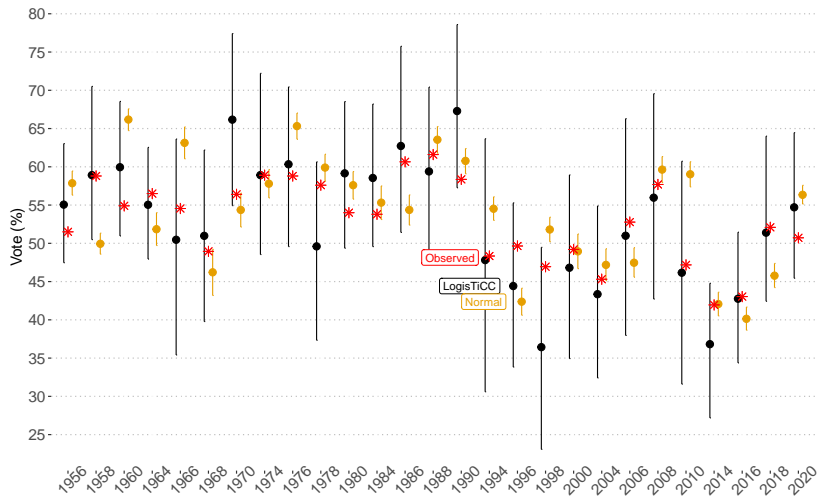
# 95% CI Coverage: Median House Seat Expected Vote



95% CI captures (Theory: 26/27): Normal 7/27,



# 95% CI Coverage: Median House Seat Expected Vote

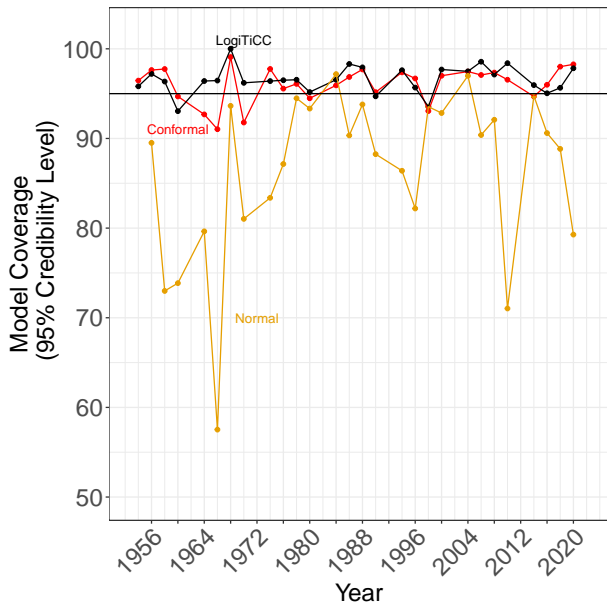


95% CI captures (Theory: 26/27): Normal 7/27, LogisTiCC 27/27

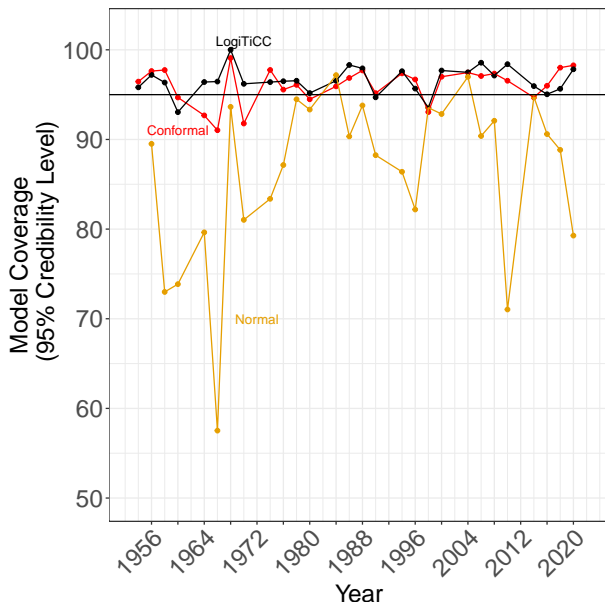
## 95% CI Coverage:

# 95% CI Coverage: District Vote

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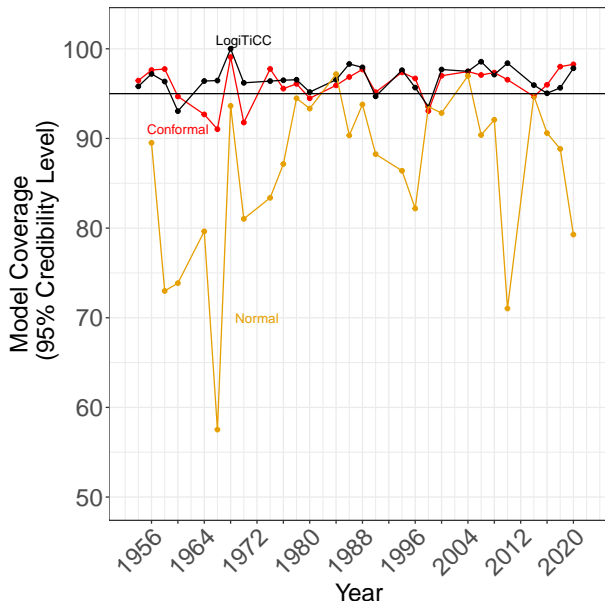


# 95% CI Coverage: District Vote



LogisTiCC:  
~ correct

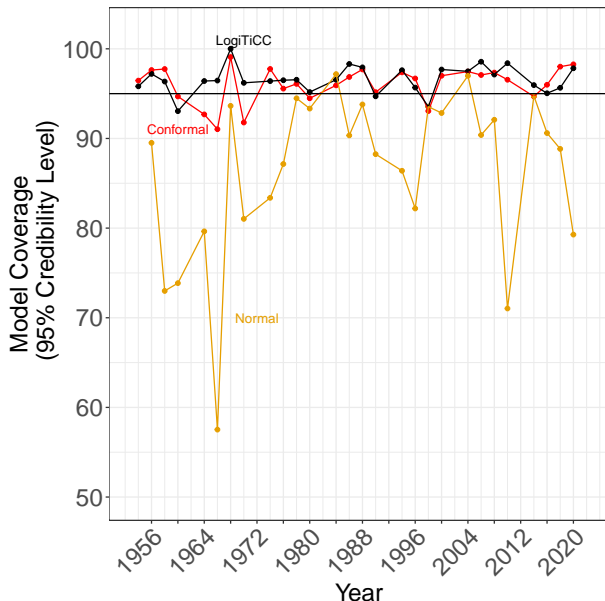
# 95% CI Coverage: District Vote



LogisTiCC:  
~ correct

Normal: Way  
over confident

# 95% CI Coverage: District Vote



LogisTiCC:  
~ correct

Normal: Way  
over confident

Nonparametric:  
~ correct

The Plan

Model Validation: Out-of-sample tests

**Prob(Incumbent Defeat): High, No Change**

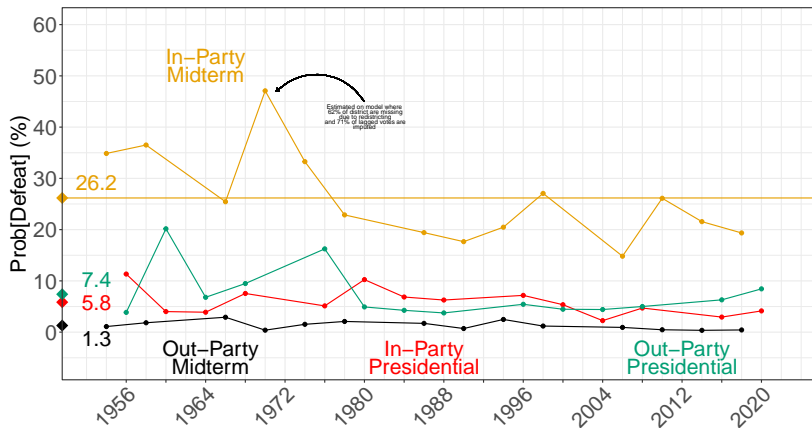
Intermediate Variables: Massive Change

How No Change Leads to Massive Change

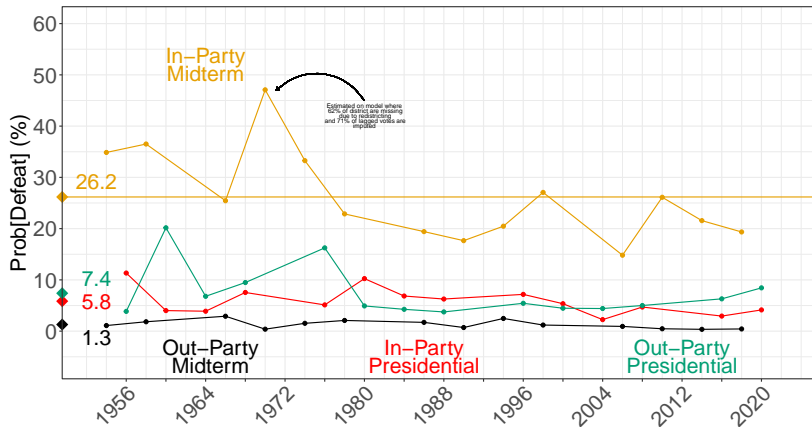


# Prob(Defeat): High Mean, No (systematic) Change

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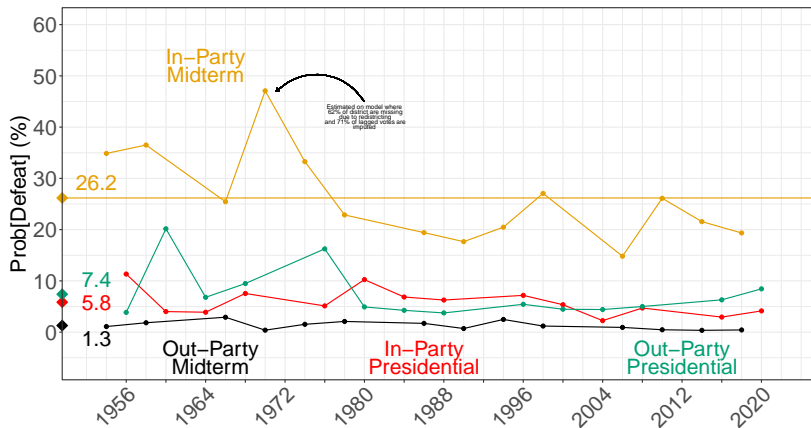


# Prob(Defeat): High Mean, No (systematic) Change



Mean high: 1.3–26.2%; overall: 11%

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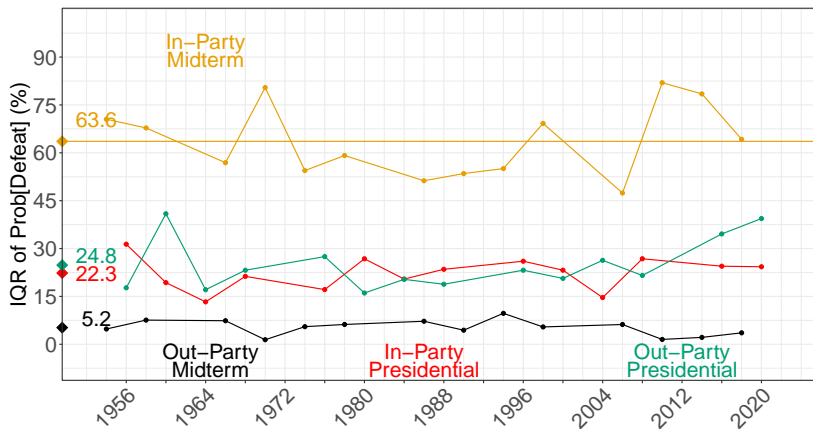


Mean high: 1.3–26.2%; overall: 11%

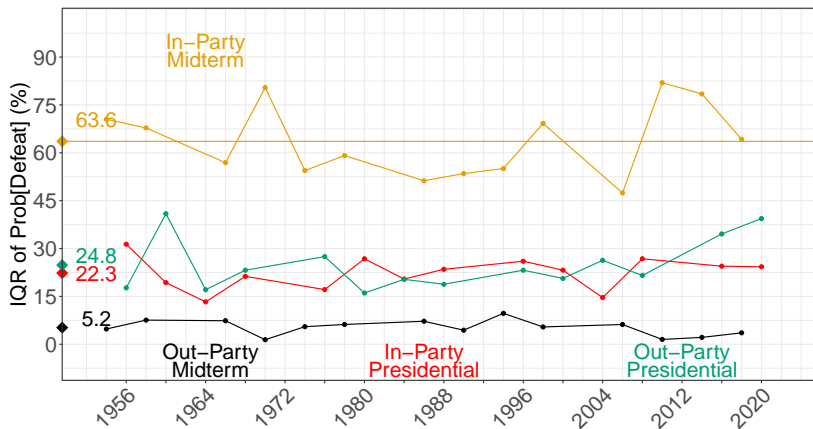
No Trend: Approximately constant over time

# Prob(Defeat): High Variation, No (systematic) Change

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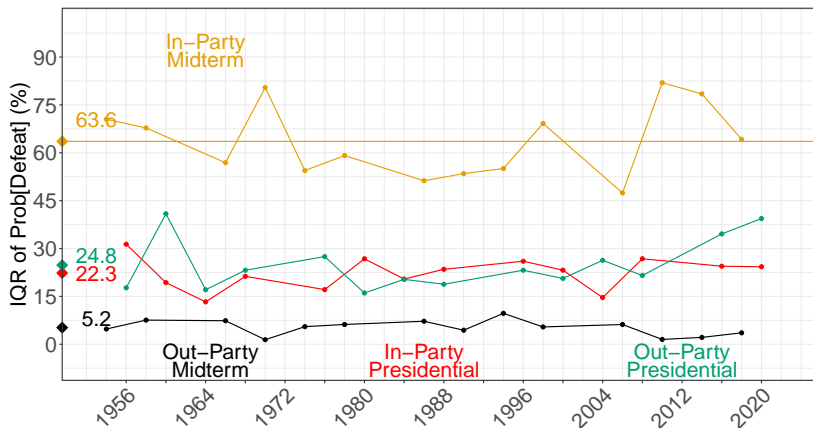


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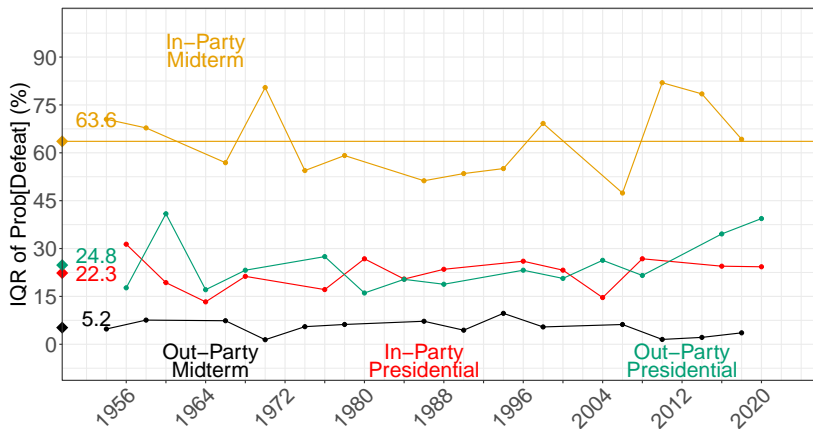


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No Trend: Approximately constant over time



# Prob(Defeat): High Variation, No (systematic) Change



Mean high: 1.3–26.2%; overall: 11%

No Trend: Approximately constant over time

Individual job security? Random terror!

The Plan

Model Validation: Out-of-sample tests

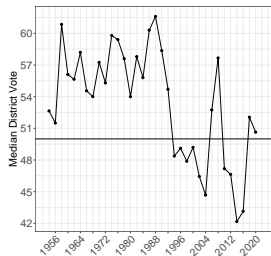
Prob(Incumbent Defeat): High, No Change

**Intermediate Variables: Massive Change**

How No Change Leads to Massive Change

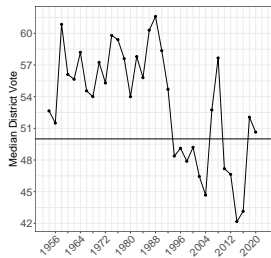
# Massive Political Change [With Prob(Defeat) constant?]

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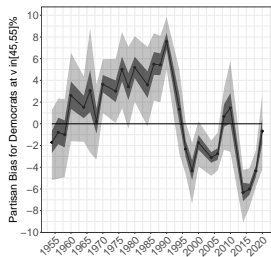


Median District Vote

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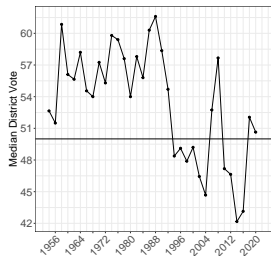


Median District Vote

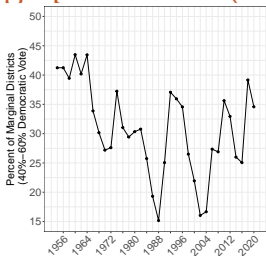


Partisan Bias

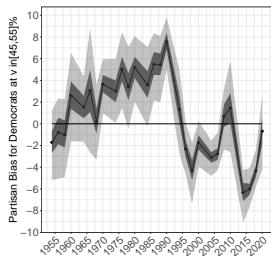
# Massive Political Change [With Prob(Defeat) constant?]



Median District Vote

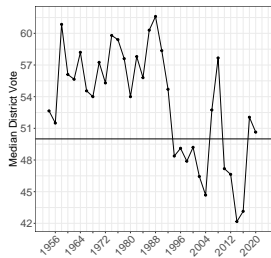


Electoral Marginals

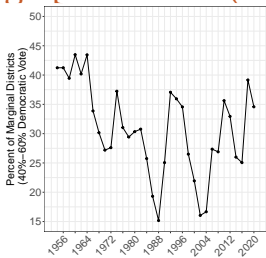


Partisan Bias

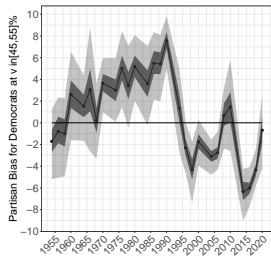
# Massive Political Change [With Prob(Defeat) constant?]



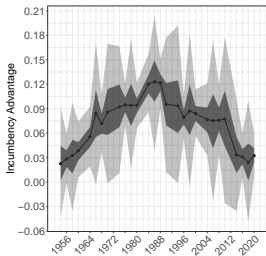
Median District Vote



Electoral Marginals

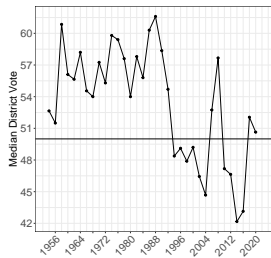


Partisan Bias

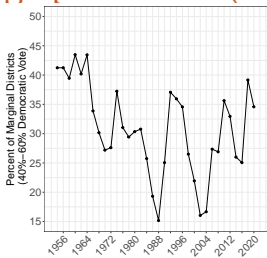


Incumbency Advantage

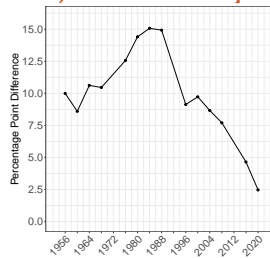
# Massive Political Change [With Prob(Defeat) constant?]



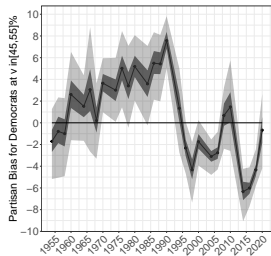
Median District Vote



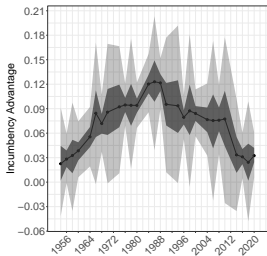
Electoral Marginals



Split Ticket Voting



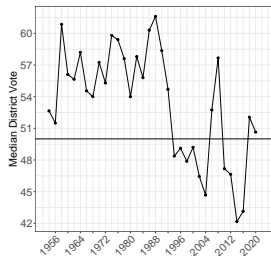
Partisan Bias



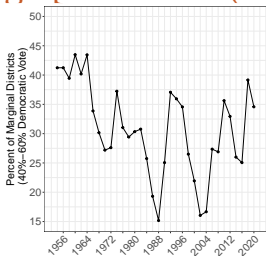
Incumbency Advantage



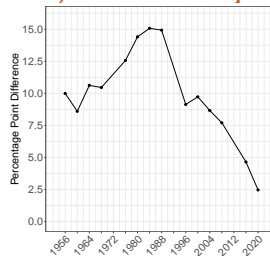
# Massive Political Change [With Prob(Defeat) constant?]



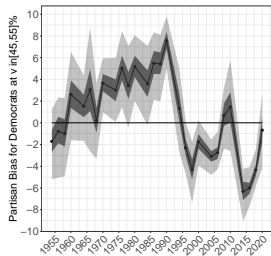
Median District Vote



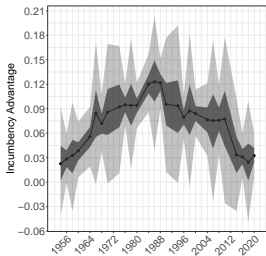
Electoral Marginals



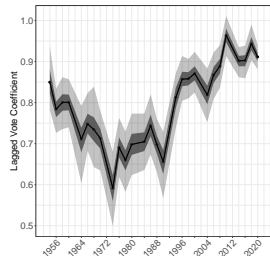
Split Ticket Voting



Partisan Bias



Incumbency Advantage



Lagged Vote

The Plan

Model Validation: Out-of-sample tests

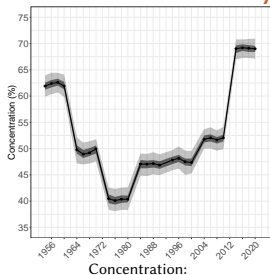
Prob(Incumbent Defeat): High, No Change

Intermediate Variables: Massive Change

How No Change Leads to Massive Change

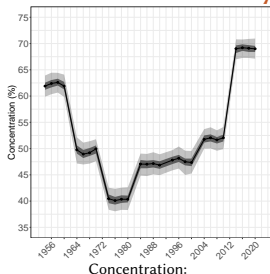
# More than Central Tendency: Variation Matters

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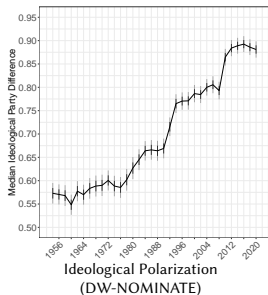
$$\int_{45}^{55} p(v|E[v] = 50)dv$$

# More than Central Tendency: Variation Matters

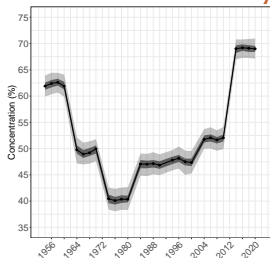


Concentration:

$$\int_{45}^{55} p(v|E[v] = 50)dv$$

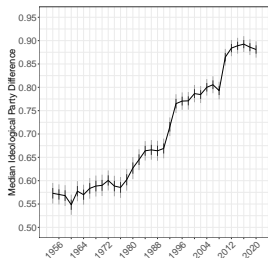


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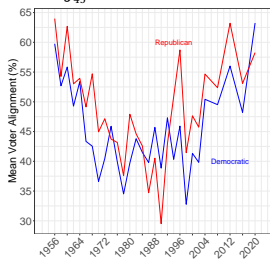


Concentration:

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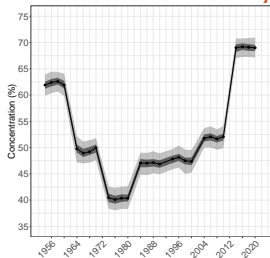


Ideological Polarization  
(DW-NOMINATE)



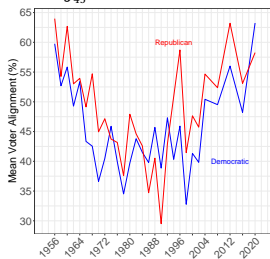
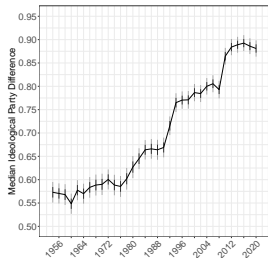
Party ID-Vote Agreement (ANES)

# More than Central Tendency: Variation Matters

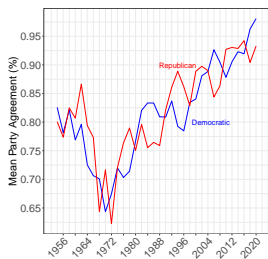


Concentration:

$$\int_{45}^{55} p(v|E[v] = 50)dv$$



Party ID-Vote Agreement (ANES)

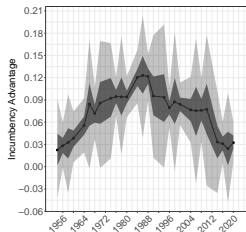


Legislator-Leader Party Agreement (Roll calls)

# “Adding” it up

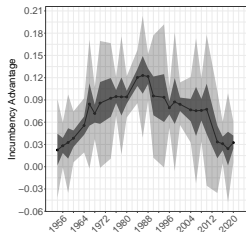


# “Adding” it up



Incumbency  
Advantage

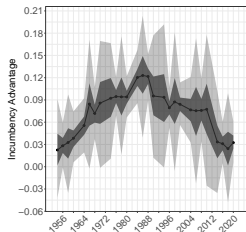
# “Adding” it up



+

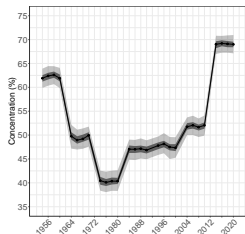
Incumbency  
Advantage

# “Adding” it up



Incumbency  
Advantage

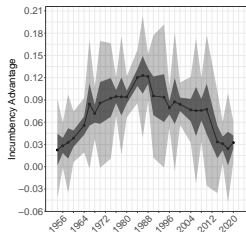
+



Concentration:

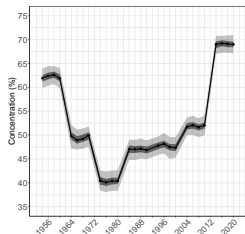
$$\int_{45}^{55} p(v|E[v] = 50)dv$$

# “Adding” it up



Incumbency  
Advantage

+

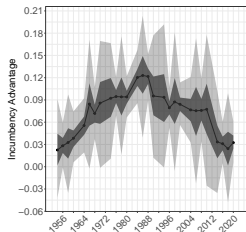


=

Concentration:

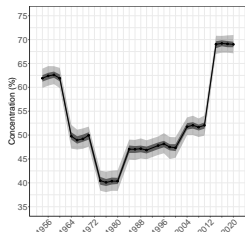
$$\int_{45}^{55} p(v|E[v] = 50)dv$$

# “Adding” it up



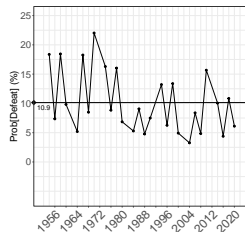
Incumbency  
Advantage

+



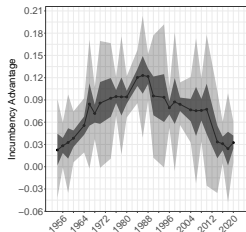
Concentration:  
$$\int_{45}^{55} p(v|E[v] = 50)dv$$

=



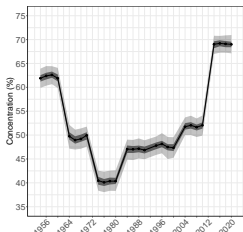
Mean Prob(Defeat)

# “Adding” it up



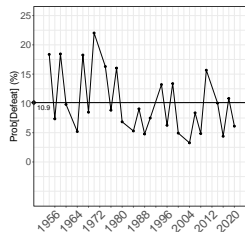
Incumbency  
Advantage

+



Concentration:  
$$\int_{45}^{55} p(v|E[v] = 50)dv$$

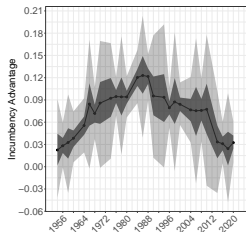
=



Mean Prob(Defeat)

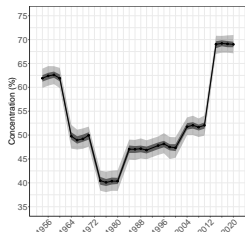
We find

# “Adding” it up



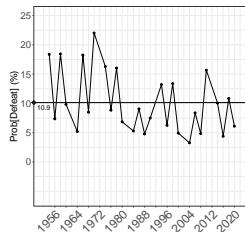
Incumbency  
Advantage

+



Concentration:  
$$\int_{45}^{55} p(v|E[v] = 50)dv$$

=

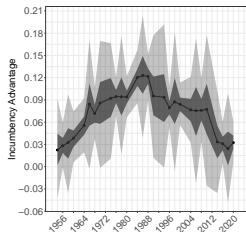


Mean Prob(Defeat)

We find

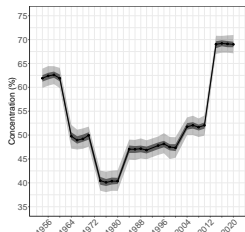
- Prob(defeat) high, constant over > 2/3rds century

# “Adding” it up



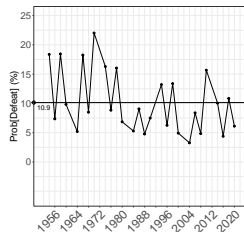
Incumbency  
Advantage

+



Concentration:  
$$\int_{45}^{55} p(v|E[v] = 50)dv$$

=



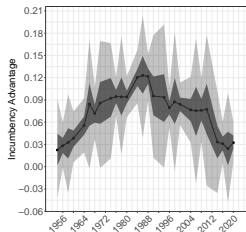
Mean Prob(Defeat)

## We find

- Prob(defeat) high, constant over > 2/3rds century
- Different combos of {Polarization, Partisanship, IncAd, Marginals, Gerrymandering bias}  $\leadsto$  the same Prob(Defeat)

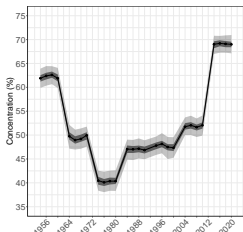


# “Adding” it up



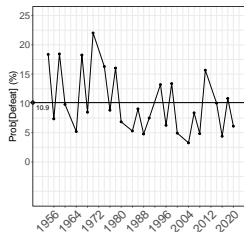
Incumbency  
Advantage

+



Concentration:  
$$\int_{45}^{55} p(v|E[v] = 50)dv$$

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Mean Prob(Defeat)

## We find

- Prob(defeat) high, constant over > 2/3rds century
- Different combos of {Polarization, Partisanship, IncAd, Marginals, Gerrymandering bias}  $\leadsto$  the same Prob(Defeat)
- (This part of) American democracy actually seems to work

Papers, slides, software, data

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