How American Politics Ensures Electoral Accountability in Congress¹

Gary King²

Institute for Quantitative Social Science Harvard University

UCLA, 3/12/2024

¹Joint with Danny Ebanks & Jonathan N. Katz ²GaryKing.org

The Plan

Model Validation: Out-of-sample tests

Prob(Incumbent Defeat): High Mean, No Trend

Intermediate Variables: Massive Change

How No Change Leads to Massive Change

The Plan 2/20.

• Controversial Indicators of Democracy (important otherwise)

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization:

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much!

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment:

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much!

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage:

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much!

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals:

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much!

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering:

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much!

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - · Definition: meaningful threat of electoral defeat
 - Quantity of interest:

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat
 - Quantity of interest: $Pr(Defeat_t|winner_{t-1} runs at t)$

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat
 - Quantity of interest: $Pr(Defeat_t|winner_{t-1} runs at t)$
 - Who chooses decisive issues? Voters, not researchers

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat
 - Quantity of interest: $Pr(Defeat_t|winner_{t-1} runs at t)$
 - Who chooses decisive issues? Voters, not researchers
 - Prior estimates: rare, none at scale

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat
 - Quantity of interest: $Pr(Defeat_t|winner_{t-1} runs at t)$
 - Who chooses decisive issues? Voters, not researchers
 - Prior estimates: rare, none at scale

We find

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat
 - Quantity of interest: $Pr(Defeat_t|winner_{t-1} runs at t)$
 - Who chooses decisive issues? Voters, not researchers
 - Prior estimates: rare, none at scale
- We find
 - Prob(Defeat) high & constant over > 2/3rds century

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat
 - Quantity of interest: $Pr(Defeat_t|winner_{t-1} runs at t)$
 - Who chooses decisive issues? Voters, not researchers
 - Prior estimates: rare, none at scale
- We find
 - Prob(Defeat) high & constant over > 2/3rds century
 - This part of American democracy actually seems to work

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat
 - Quantity of interest: $Pr(Defeat_t|winner_{t-1} runs at t)$
 - Who chooses decisive issues? Voters, not researchers
 - Prior estimates: rare, none at scale
- We find
 - Prob(Defeat) high & constant over > 2/3rds century
 - This part of American democracy actually seems to work

• But Wait! Why then do the indicators change so much?

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat
 - Quantity of interest: $Pr(Defeat_t|winner_{t-1} runs at t)$
 - Who chooses decisive issues? Voters, not researchers
 - Prior estimates: rare, none at scale
- We find
 - Prob(Defeat) high & constant over > 2/3rds century
 - This part of American democracy actually seems to work
- But Wait! Why then do the indicators change so much?
 - E.g., Incumbency Advantage ∈ [2, 10] percentage points?

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat
 - Quantity of interest: $Pr(Defeat_t|winner_{t-1} runs at t)$
 - Who chooses decisive issues? Voters, not researchers
 - Prior estimates: rare, none at scale
- We find
 - Prob(Defeat) high & constant over > 2/3rds century
 - This part of American democracy actually seems to work
- But Wait! Why then do the indicators change so much?
 - E.g., Incumbency Advantage $\in [2, 10]$ percentage points?
 - Prior research: central tendency;

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat
 - Quantity of interest: $Pr(Defeat_t|winner_{t-1} runs at t)$
 - Who chooses decisive issues? Voters, not researchers
 - Prior estimates: rare, none at scale
- We find
 - Prob(Defeat) high & constant over > 2/3rds century
 - This part of American democracy actually seems to work
- But Wait! Why then do the indicators change so much?
 - E.g., Incumbency Advantage $\in [2, 10]$ percentage points?
 - Prior research: central tendency; Ours: full distribution

- Controversial Indicators of Democracy (important otherwise)
 - Ideological polarization: Now: Too much! 1950s: Too little!
 - Partisan alignment: Now: too much! 1980s: too little!
 - Incumbency advantage: 1980s: too much! Now: shh!
 - Vanishing marginals: 1970s: too much! 1980s: nope!
 - Gerrymandering: 200+ years: too much! SCOTUS: it's ok
- Uncontroversial Indicator: Electoral Accountability
 - Definition: meaningful threat of electoral defeat
 - Quantity of interest: $Pr(Defeat_t|winner_{t-1} runs at t)$
 - Who chooses decisive issues? Voters, not researchers
 - Prior estimates: rare, none at scale
- We find
 - Prob(Defeat) high & constant over > 2/3rds century
 - This part of American democracy actually seems to work
- But Wait! Why then do the indicators change so much?
 - E.g., Incumbency Advantage $\in [2, 10]$ percentage points?
 - Prior research: central tendency; Ours: full distribution
 - Different combos of {Polarization, Partisanship, IncAd, Marginals, Gerrymandering bias} → the same Prob(Defeat)

The Plan 3/20.

Goal: DGP, not merely Causal Effects

Goal: DGP, not merely Causal Effects

Causality

Goal: DGP, not merely Causal Effects

Causality

Beyond Causality: The DGP

Causality

Beyond Causality: The DGP

Estimating the DGP

- Causality
 - More progress recently than in 2000 years

• Beyond Causality: The DGP

Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
- Beyond Causality: The DGP

Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects:
- Beyond Causality: The DGP

• Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP

• Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description:

• Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes?

• Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes?

• Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes? Must be generatively accurate

• Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes? Must be generatively accurate
 - Explanation:

Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes? Must be generatively accurate
 - Explanation: Why did it happen?

• Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes? Must be generatively accurate
 - Explanation: Why did it happen? Who did it?

• Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes? Must be generatively accurate
 - Explanation: Why did it happen? Who did it?
 - "Causes of Effects" rather than "Effects of Causes"

• Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes? Must be generatively accurate
 - Explanation: Why did it happen? Who did it?
 - "Causes of Effects" rather than "Effects of Causes"
 - Our purpose: The big picture for Prob(defeat) & lots more

Estimating the DGP

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes? Must be generatively accurate
 - Explanation: Why did it happen? Who did it?
 - "Causes of Effects" rather than "Effects of Causes"
 - Our purpose: The big picture for Prob(defeat) & lots more
- Estimating the DGP
 - · Build: a generative model

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes? Must be generatively accurate
 - Explanation: Why did it happen? Who did it?
 - "Causes of Effects" rather than "Effects of Causes"
 - Our purpose: The big picture for Prob(defeat) & lots more
- Estimating the DGP
 - · Build: a generative model
 - Validate: with extensive out-of-sample forecasts

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes? Must be generatively accurate
 - Explanation: Why did it happen? Who did it?
 - "Causes of Effects" rather than "Effects of Causes"
 - Our purpose: The big picture for Prob(defeat) & lots more
- Estimating the DGP
 - · Build: a generative model
 - Validate: with extensive out-of-sample forecasts
 - Compute: descriptive summaries of all quantities

- Causality
 - More progress recently than in 2000 years
 - Quantity of Interest: Y(1) Y(0) (specific, narrow)
 - Knowledge of all causal effects: insufficient
- Beyond Causality: The DGP
 - Description: Anything goes? Must be generatively accurate
 - Explanation: Why did it happen? Who did it?
 - "Causes of Effects" rather than "Effects of Causes"
 - Our purpose: The big picture for Prob(defeat) & lots more
- Estimating the DGP
 - · Build: a generative model
 - Validate: with extensive out-of-sample forecasts
 - Compute: descriptive summaries of all quantities

• Interpret: to understand the big picture

The Plan 4/20.

• Data: 14,710 Congressional district elections, 1954–2020

- Data: 14,710 Congressional district elections, 1954–2020
- v_{it} : Dem vote proportion

- Data: 14,710 Congressional district elections, 1954–2020
- *v*_{it}: Dem vote proportion
- X_{it} : lag(vote), Inc party, Inc status, uncontestedness, South

- Data: 14,710 Congressional district elections, 1954–2020
- v_{it} : Dem vote proportion
- X_{it} : lag(vote), Inc party, Inc status, uncontestedness, South

$$v_{it} \sim \mathcal{N}(\mu_{it}, \sigma^2)$$
 Regression $\mu_{it} = X_{it}\beta_t$

- Data: 14,710 Congressional district elections, 1954–2020
- *v*_{it}: Dem vote proportion
- X_{it} : lag(vote), Inc party, Inc status, uncontestedness, South

$$v_{it} \sim \mathcal{N}(\mu_{it}, \sigma^2)$$
 Gelman-King's Judgelt $\mu_{it} = X_{it}\beta_t + \gamma_i$

• District Uniqueness: $\gamma_i \sim \mathcal{N}(0, \sigma_{\gamma}^2)$

- Data: 14,710 Congressional district elections, 1954–2020
- *v*_{it}: Dem vote proportion
- X_{it} : lag(vote), Inc party, Inc status, uncontestedness, South

$$v_{it} \sim \mathcal{N}(\mu_{it}, \sigma^2)$$

$$\mu_{it} = X_{it}\beta_t + \gamma_i + \eta_t$$

- District Uniqueness: $\gamma_i \sim \mathcal{N}(0, \sigma_{\gamma}^2)$
- National Swing: $\eta_t \sim \mathcal{N}(0, \sigma_n^2)$

- Data: 14,710 Congressional district elections, 1954–2020
- v_{it} : Dem vote proportion
- X_{it} : lag(vote), Inc party, Inc status, uncontestedness, South

$$v_{it} \sim \mathcal{N}(\mu_{it}, \sigma^2)$$

$$\mu_{it} = X_{it} \frac{\beta_t}{\beta_t} + \gamma_i + \eta_t$$

- District Uniqueness: $\gamma_i \sim \mathcal{N}(0, \sigma_v^2)$
- National Swing: $\eta_t \sim \mathcal{N}(0, \sigma_\eta^2)$
- Coeff. Stability: $\beta_t \sim \mathcal{N}(\bar{\beta}, \sigma_{\beta}^2) \sim$ Midterm penalty, Early exits

- Data: 14,710 Congressional district elections, 1954–2020
- *v*_{it}: Dem vote proportion
- X_{it} : lag(vote), Inc party, Inc status, uncontestedness, South

$$v_{it} \sim ALT(\mu_{it}, \sigma^2, v_t)$$
 LogisTiCC
 $\mu_{it} = X_{it} \frac{\beta_t}{\beta_t} + \gamma_t + \eta_t$

- District Uniqueness: $\gamma_i \sim \mathcal{N}(0, \sigma_v^2)$
- National Swing: $\eta_t \sim \mathcal{N}(0, \sigma_\eta^2)$
- Coeff. Stability: $\beta_t \sim \mathcal{N}(\bar{\beta}, \sigma_{\beta}^2) \rightsquigarrow \text{Midterm penalty, Early exits}$
- Surprises (nonlinear, nonnormal): $\ln[v_{it}/(1-v_{it})] \sim t(\mu_{it}, \sigma, v_t)$

- Data: 14,710 Congressional district elections, 1954–2020
- *v*_{it}: Dem vote proportion
- X_{it} : lag(vote), Inc party, Inc status, uncontestedness, South

$$v_{it} \sim ALT(\mu_{it}, \sigma^2, v_t)$$
 LogisTiCC
 $\mu_{it} = X_{it} \frac{\beta_t}{\beta_t} + \gamma_t + \eta_t$

- District Uniqueness: $\gamma_i \sim \mathcal{N}(0, \sigma_\gamma^2)$
- National Swing: $\eta_t \sim \mathcal{N}(0, \sigma_\eta^2)$
- Coeff. Stability: $\beta_t \sim \mathcal{N}(\bar{\beta}, \sigma_{\beta}^2) \rightsquigarrow \text{Midterm penalty, Early exits}$
- Surprises (nonlinear, nonnormal): $\ln[v_{it}/(1-v_{it})] \sim t(\mu_{it}, \sigma, v_t)$

• Ablation studies: every component essential

- Data: 14,710 Congressional district elections, 1954–2020
- *v*_{it}: Dem vote proportion
- X_{it} : lag(vote), Inc party, Inc status, uncontestedness, South

$$v_{it} \sim ALT(\mu_{it}, \sigma^2, v_t)$$
 LogisTiCC
 $\mu_{it} = X_{it} \frac{\beta_t}{\beta_t} + \gamma_t + \eta_t$

- District Uniqueness: $\gamma_i \sim \mathcal{N}(0, \sigma_{\gamma}^2)$
- National Swing: $\eta_t \sim \mathcal{N}(0, \sigma_\eta^2)$
- Coeff. Stability: $\beta_t \sim \mathcal{N}(\bar{\beta}, \sigma_{\beta}^2) \rightsquigarrow \text{Midterm penalty, Early exits}$
- Surprises (nonlinear, nonnormal): $\ln[v_{it}/(1-v_{it})] \sim t(\mu_{it}, \sigma, v_t)$
- Ablation studies: every component essential
- Extensions: uncontested outcomes; > 2 parties

- Data: 14,710 Congressional district elections, 1954–2020
- *v*_{it}: Dem vote proportion
- X_{it} : lag(vote), Inc party, Inc status, uncontestedness, South

$$v_{it} \sim ALT(\mu_{it}, \sigma^2, v_t)$$
 LogisTiCC
 $\mu_{it} = X_{it} \frac{\beta_t}{\beta_t} + \gamma_i + \eta_t$

- District Uniqueness: $\gamma_i \sim \mathcal{N}(0, \sigma_{\gamma}^2)$
- National Swing: $\eta_t \sim \mathcal{N}(0, \sigma_\eta^2)$
- Coeff. Stability: $\beta_t \sim \mathcal{N}(\bar{\beta}, \sigma_{\beta}^2) \sim \text{Midterm penalty, Early exits}$
- Surprises (nonlinear, nonnormal): $\ln[v_{it}/(1-v_{it})] \sim t(\mu_{it}, \sigma, v_t)$
- Ablation studies: every component essential
- Extensions: uncontested outcomes; > 2 parties
- Computation: extensive but easy; ElectIt Software

The Plan 5/20.

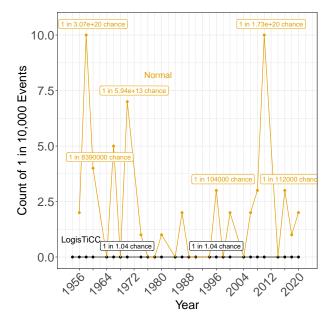
The Plan

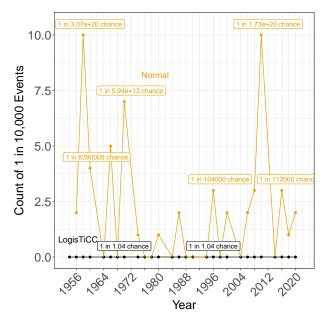
Model Validation: Out-of-sample tests

Prob(Incumbent Defeat): High Mean, No Trend

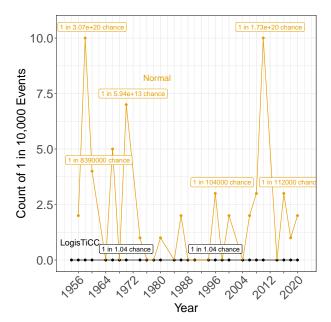
Intermediate Variables: Massive Change

How No Change Leads to Massive Change



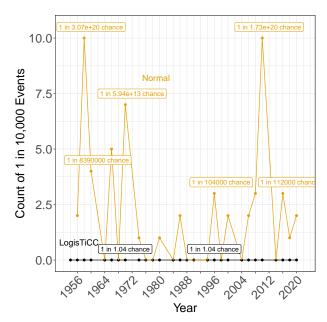


1-in-10K Events:



1-in-10K Events:

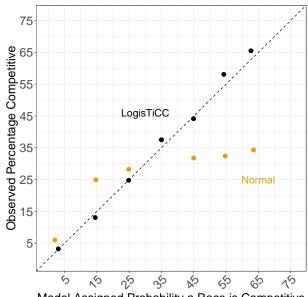
LogisTiCC: 0 in 10K



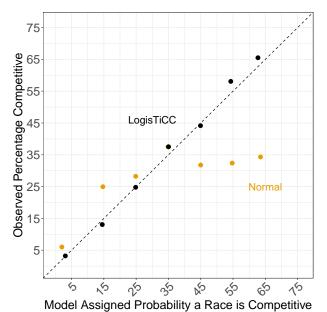
1-in-10K Events:

LogisTiCC: 0 in 10K

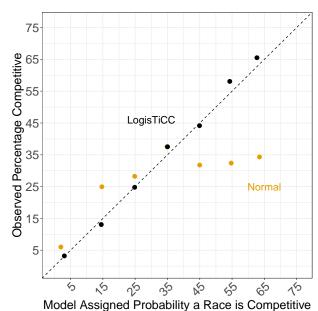
Normal: All the time!



Model Assigned Probability a Race is Competitive



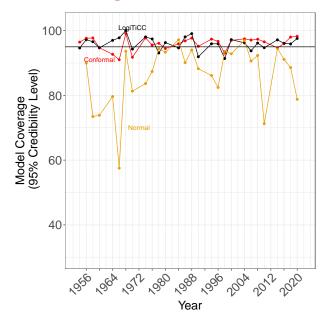
LogisTiCC: Near perfect

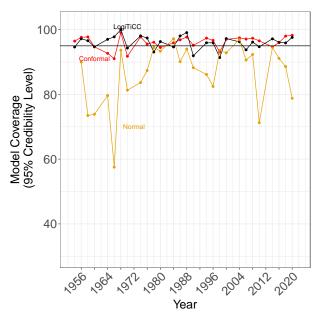


LogisTiCC: Near perfect

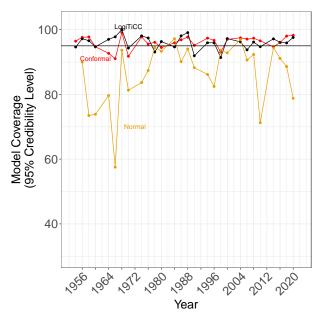
Normal: Fails for the most important elections

95% CI Coverage:



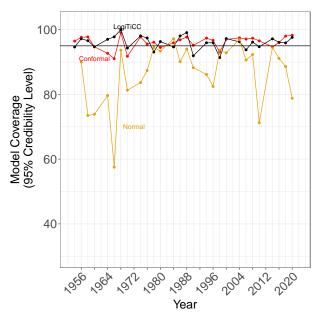


LogisTiCC: ~ correct



LogisTiCC: ~ correct

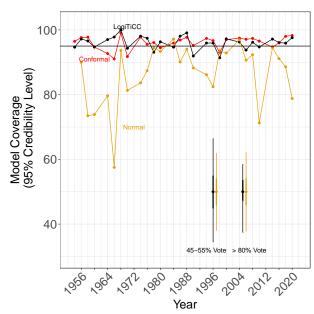
Normal: Way over confident



LogisTiCC: ~ correct

Normal: Way over confident

Nonparametric: ~ correct



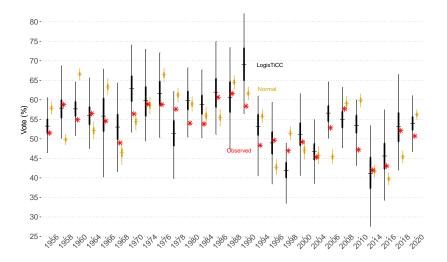
LogisTiCC: ~ correct

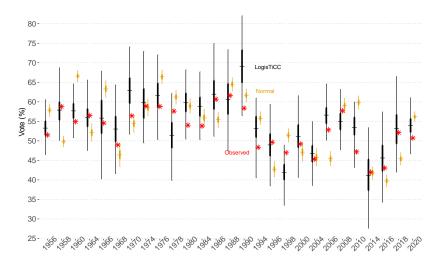
Normal: Way over confident

Nonparametric: ~ correct

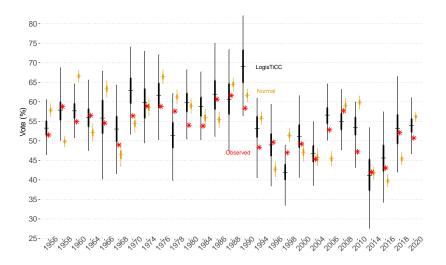
Average CI Width

95% CI Coverage:

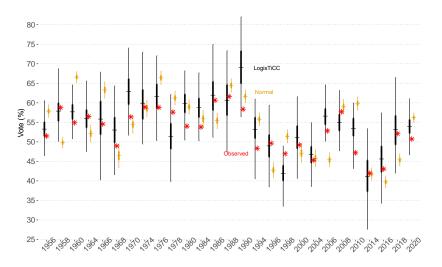




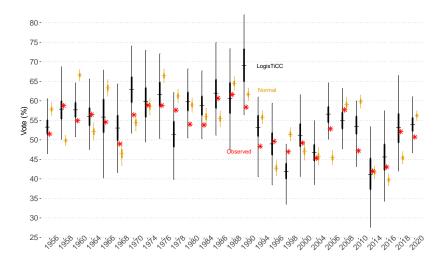
95% CI captures



95% CI captures (Theory: 26/27):



95% CI captures (Theory: 26/27): Normal 7/27,



95% CI captures (Theory: 26/27): Normal 7/27, LogisTiCC 27/27

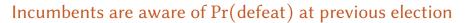
The Plan

Model Validation: Out-of-sample tests

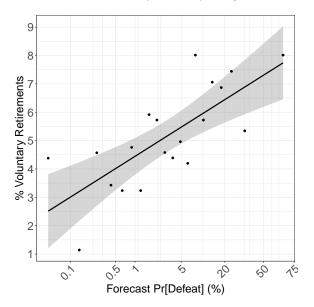
Prob(Incumbent Defeat): High Mean, No Trend

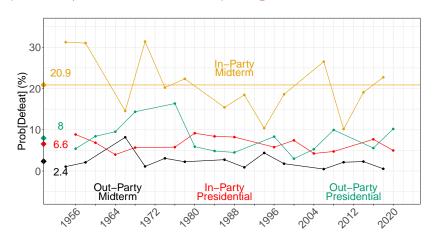
Intermediate Variables: Massive Change

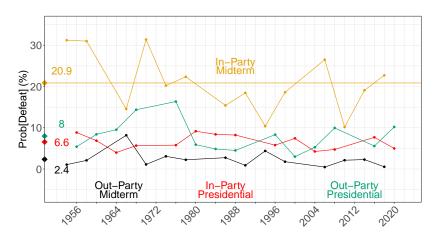
How No Change Leads to Massive Change



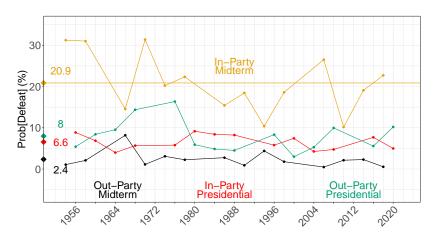
Incumbents are aware of Pr(defeat) at previous election







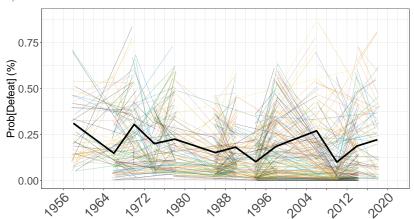
High Mean: 2.4-20.9%; overall: 11%



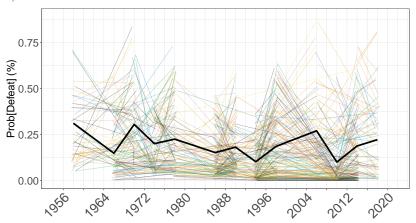
High Mean: 2.4–20.9%; overall: 11% No Trend

In Party, Midterm

In Party, Midterm

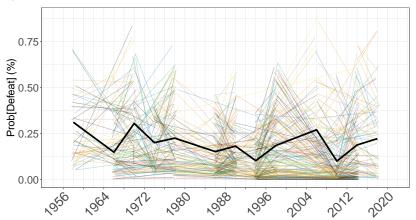


In Party, Midterm



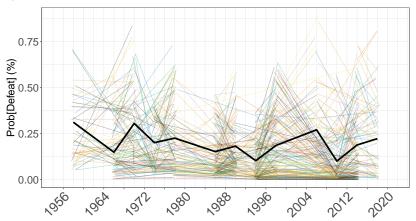
Mean: High

In Party, Midterm



Mean: High Trends: None

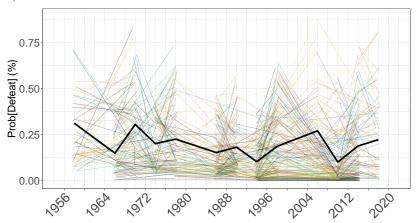
In Party, Midterm



Mean: High Trends: None

Individual Variation: Massive

In Party, Midterm

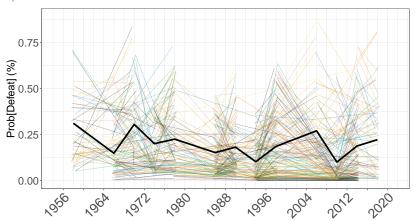


Mean: High Trends: None

Individual Variation: Massive

Job security?

In Party, Midterm



Mean: High Trends: None

Individual Variation: Massive

Job security? Random terror!

The Plan

Model Validation: Out-of-sample tests

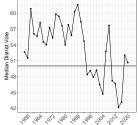
Prob(Incumbent Defeat): High Mean, No Trend

Intermediate Variables: Massive Change

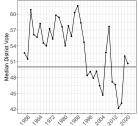
How No Change Leads to Massive Change

Massive Political Change [With Prob(Defeat) constant?]

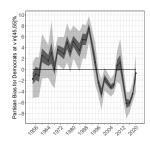
Massive Political Change [With Prob(Defeat) constant?]



Median District Vote



Median District Vote

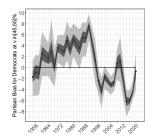




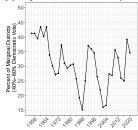
50 Janeau of Nardona Districts Committee of the Committee

Median District Vote

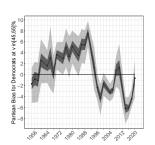
Electoral Marginals





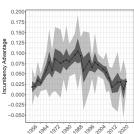


Median District Vote



Partisan Bias

Electoral Marginals



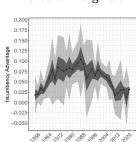


500 \$1,000 (and) 400 \$1,000



Split Ticket Voting

Median District Vote



Electoral Marginals

Partisan Bias

1964 1910 1980 1980 1980 2004 2017 2020

Incumbency Advantage

Partisan Bias for Democrats at v in[45,55]%

Massive Political Change [With Prob(Defeat) constant?] 15.0 Percentage Point Difference 12.5 Median District Vote 5.0 2.5 45 42 0.0 ,96^A ,971 ,980 ,988 Median District Vote Split Ticket Voting **Electoral Marginals** Partisan Bias for Democrats at v in[45,55]% 0.175 0.150 0.125 0.100 0.075 0.050 0.025 0.000 -0.025 -0.050 1964 1910 1980 1980 1980 2004 2017 2020 "de "de "du "de "de "de "de "du "du "du Partisan Bias Incumbency Advantage Lagged Vote Intermediate Variables: Massive Change 16/20.

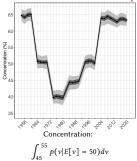
The Plan

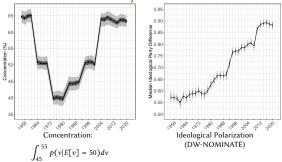
Model Validation: Out-of-sample tests

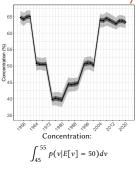
Prob(Incumbent Defeat): High Mean, No Trend

Intermediate Variables: Massive Change

How No Change Leads to Massive Change



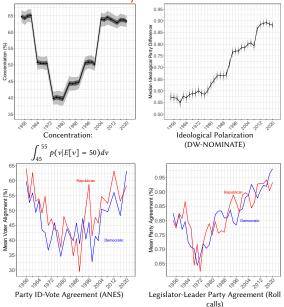


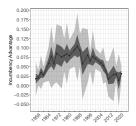




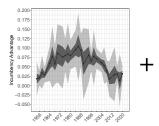


calls)

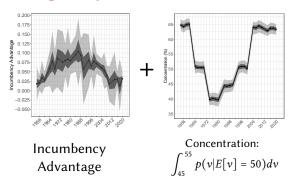


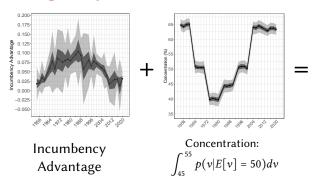


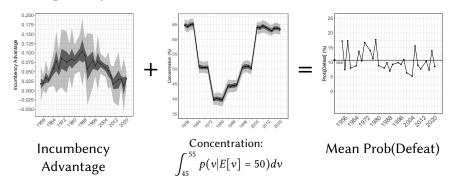
Incumbency Advantage

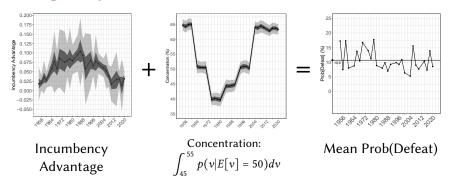


Incumbency Advantage

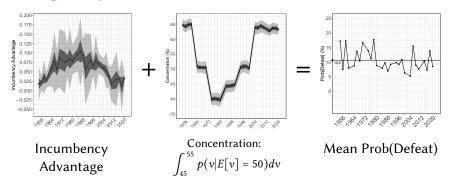






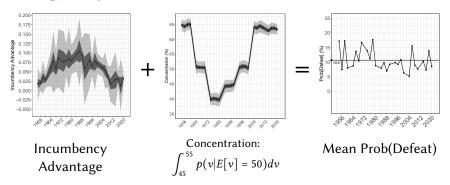


We find



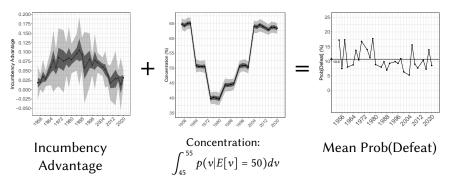
We find

Prob(defeat) high, constant over > 2/3rds century



We find

- Prob(defeat) high, constant over > 2/3rds century
- Different combos of {Polarization, Partisanship, IncAd, Marginals, Gerrymandering bias} → the same Prob(Defeat)



We find

- Prob(defeat) high, constant over > 2/3rds century
- Different combos of {Polarization, Partisanship, IncAd, Marginals, Gerrymandering bias} → the same Prob(Defeat)
- (This part of) American democracy actually seems to work

Papers, slides, software, data

GaryKing.org

